Depth-First Search

Toshiaki Nishihara Yasuhiko Minamide

June 16, 2019

Abstract

Depth-first search of a graph is formalized with `function`. It is shown that it visits all of the reachable nodes from a given list of nodes. Executable ML code of depth-first search is obtained with code generation feature of Isabelle/HOL. The formalization contains two implementations of depth-first search: one by stack and one by nested recursion. They are shown to be equivalent. The termination condition of the version with nested-recursion is shown by the method of inductive invariants.

Contents

1 Depth-First Search

theory *DFS*
imports *Main*
begin

1.1 Definition of Graphs

typedecl *node*
type-synonym *graph* = (*node* ∗ *node*) *list*

primrec *nexts* :: [*graph*, *node*] ⇒ *node list*
where
  nexts [] *n* = []
| *nexts* (*e*#*es*) *n* = (*if fst e* = *n then snd e* # *nexts es n else nexts es n*)

definition *nextss* :: [*graph*, *node list*] ⇒ *node set*
where *nextss g xs* = *set g* `` *set xs*

lemma *nexts-set*: *y* ∈ *set* (*nexts g x*) = ((*x*,*y*) ∈ *set g*)
⟨*proof*⟩

lemma *nextss-Cons*: *nextss g* (*x*#*xs*) = *set* (*nexts g x*) ∪ *nextss g xs*
⟨*proof*⟩

definition *reachable* :: [*graph*, *node list*] ⇒ *node set*
where *reachable g xs* = (*set g*)* `` *set xs*

1.2 Depth-First Search with Stack

definition *nodes-of* :: *graph* ⇒ *node set*
where *nodes-of g* = *set* (*map fst g* @ *map snd g*)

lemma [*simp*]: *x* ∉ *nodes-of g* ⟹ *nexts g x* = []
⟨*proof*⟩

lemma [*simp*]: *finite* (*nodes-of g* − *set ys*)
⟨*proof*⟩

function
dfs :: *graph* ⇒ *node list* ⇒ *node list* ⇒ *node list*
where
dfs-base: *dfs g* [] *ys* = *ys*
| *dfs-inductive*: *dfs g* (*x*#*xs*) *ys* = (*if List.member ys x then dfs g xs ys*
else dfs g (*nexts g x*@*xs*) (*x*#*ys*))
⟨*proof*⟩

termination
⟨*proof*⟩

- The second argument of *dfs* is a stack of nodes that will be visited.
- The third argument of *dfs* is a list of nodes that have been visited already.

1.3 Depth-First Search with Nested-Recursion

function
dfs2 :: *graph* ⇒ *node list* ⇒ *node list* ⇒ *node list*
where
dfs2 g [] *ys* = *ys*
| *dfs2-inductive*:
dfs2 g (*x*#*xs*) *ys* = (*if List.member ys x then dfs2 g xs ys*

else dfs2 g xs (dfs2 g (nexts g x) (x#ys)))
⟨*proof*⟩

lemma *dfs2-invariant*: *dfs2-dom* (*g*, *xs*, *ys*) ⟹ *set ys* ⊆ *set* (*dfs2 g xs ys*)
⟨*proof*⟩

termination *dfs2*
⟨*proof*⟩

lemma *dfs-app*: *dfs g* (*xs*@*ys*) *zs* = *dfs g ys* (*dfs g xs zs*)
⟨*proof*⟩

lemma *dfs2 g xs ys* = *dfs g xs ys*
⟨*proof*⟩

1.4 Basic Properties

lemma *visit-subset-dfs*: *set ys* ⊆ *set* (*dfs g xs ys*)
⟨*proof*⟩

lemma *next-subset-dfs*: *set xs* ⊆ *set* (*dfs g xs ys*)
⟨*proof*⟩

lemma *nextss-closed-dfs'*[*rule-format*]:
nextss g ys ⊆ *set xs* ∪ *set ys* ⟶ *nextss g* (*dfs g xs ys*) ⊆ *set* (*dfs g xs ys*)
⟨*proof*⟩

lemma *nextss-closed-dfs*: *nextss g* (*dfs g xs* []) ⊆ *set* (*dfs g xs* [])
⟨*proof*⟩

lemma *Image-closed-trancl*: **assumes** *r* `` *X* ⊆ *X* **shows** *r*\* `` *X* = *X*
⟨*proof*⟩

lemma *reachable-closed-dfs*: *reachable g xs* ⊆ *set*(*dfs g xs* [])
⟨*proof*⟩

lemma *reachable-nexts*: *reachable g* (*nexts g x*) ⊆ *reachable g* [*x*]
⟨*proof*⟩

lemma *reachable-append*: *reachable g* (*xs* @ *ys*) = *reachable g xs* ∪ *reachable g ys*
⟨*proof*⟩

lemma *dfs-subset-reachable-visit-nodes*: *set* (*dfs g xs ys*) ⊆ *reachable g xs* ∪ *set ys*
⟨*proof*⟩

1.5 Correctness

theorem *dfs-eq-reachable*: *set* (*dfs g xs* []) = *reachable g xs*
⟨*proof*⟩

theorem *y* ∈ *set* (*dfs g* [*x*] []) = ((*x*,*y*) ∈ (*set g*)*)
⟨*proof*⟩

1.6 Executable Code

consts *Node* :: *int* ⇒ *node*

code-datatype *Node*

instantiation *node* :: *equal*
begin

definition *equal-node* :: *node* ⇒ *node* ⇒ *bool*
where
[*code del*]: *equal-node* = *HOL.eq*

instance ⟨*proof*⟩

end

declare [[*code abort*: *HOL.equal* :: *node* ⇒ *node* ⇒ *bool*]]

export-code *dfs dfs2* **in** *SML* **file** ‹*dfs.ML*›

end